Building machines

The tasks:

- choose the right machines for the works
- plan the using of the machines
- choose the most economical method for the works

Building machines



The type of the machines*:

- hand-tools (boring machine, cutting machine)-for simple use, without planning.
- **simple tools** (concrete mixer, plaster mixer...) we must prepare to the using with a simple site plan (because we want to use energy and some building materials for the works).
- heavy machines (main machine)-You have to make a site plan for the works.

Earthwork machines



The machines by the technologically sequencing:

- Ground surface planning
- Surface ripping/dozers prepare to the cutting
- Scrapers, graders
- Excavators
- Soil loading (prepare to the transport)
- Soil dumping
- Soil compacting

Earthwork machines





- 1.1 Ground surface planning
- With special machines: stone collector, bush cutter. We prepare the ground to next works.
- Hydraulic excavator attachments:
- Wood/bush cutter, root remover attachment
- Stone collector,
- Ripping attachment.

The main machine is the dozer by the ripping.









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Soil ripping machines





• Surface ripping/dozers prepare to the cutting

Before the cutting we have to ripping **the solid surface** of the soil.

This way we can prepare to the next work phases - for

graders,

scrapers,

excavators...

Soil ripping machines





- Structure of the ripping attachment
- Moved with hydraulic cylinders:
- High pressure in the cylinder (about 6tons)
- Hanging attachment back of the bulldozers:

Big efficiency, Frame from strong steel, moved with hydraulic cylinders.

We can change the deep of the ripping with these hydraulic cylinders.

Soil ripping attachments



- a straight
- b, c curved
- d, e, f with steel blade

- <u>The structure of the teeth*:</u> It's depend on the type of soils. The angle of the ripping: 35-45°
- **<u>Straight</u>** in the case: deeper than 80 cm
- Curved soil with stones, until 80cm
- <u>Special(with blade)</u> soil with stones, until 80cm
- Distance of the teeth:
- 0,80-1,00 m, by heavy machines
- 0,90-1,3 m, by normal machines





• Bulldozers: with tracked or wheeled undercarriage.

We can use it for:

- Cutting of the soil
- Move the soil
- Fill up a ditch
- Cutting the topsoil

- The distance of the moving*:
- Wheeled machines: 100-150m
- Caterpillar tracked 60-80 m

α



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9. swivel cylinders





"Oval drive" (track)



"Delta drive" (track)

Advantages of delta drive:

- due to elevated engine and drive
- risk of getting dust (mud) in is less
- longer operation (life) time
- increased bulk clearance

Disadvantages of delta drive:

- higher costs of manufacturing
- more components, longer crawler belt

<image>

Bulldozer equipped with ripper attachment

Up-to-date controls



Laser control



Satellite control



• The main parts of the blade*:

1 - Front plate:

a curved welded steel plate

2 - Head plate:

a straight welded steel plate

3 - Side plates:

both sides of the blade- to reduce the soil losses.

4 - Cutter:

Heat-treated steel / bolted to the bottom of the blade /

5 - Bolts:

Fixation to the mainframe

Scrapers





- We can use the scrapers for the*:
- Excavating of the soil
- Hauling (and compacting)
- Discharging (spreading and compacting)
- By the construction of linear structures

(roads, dams, large surface excavations).

• The main part of scraper is:

the scraper bowl

Scrapers*

Phases of a cycle (turn)



Excavating (charging): apron up (open), bowl down (penetrating into the soil)



Hauling (and compacting): apron down (close), bowl up



Discharging (spreading and compacting): apron up (open), bowl up, ejector forward

Scrapers



Scrapers



- The thickness of the cutting is: 120 500 mm .
- The soil should not contain stones . We have to work with these machines in the IV.th soil class but we have to use ripping too.
- Hauled scrapers economically distance: 300 500
- Mobile scrapers:5000 8000
- The large of the bowl:
- Small (5 m3)
- Middle sized(5 12 m3)
- Big (over 12 m3)
- In Hungary the most popular size : 3 10m3.

Graders*





- Mainly for road construction, road crown designs are applied.
- In addition to the construction of roads suitable for performing a wide variety of work:
- To make road profiling
- Landscaping
- To making slopes

Graders



Graders

Typical application: refinery earthworks, levelling, topsoil excavation, spreading



Laser controlled (C) grader equipped with ripper (A) and front blade (B) attachment

Graders





- The **positions of the blade** are changeable.
- The angle of the suspension is different on a horizontal and on a sloping terrain. (changeable)
- This way the graders can be work more safely.
- We can change the angle of the suspension with hydraulic cylinders.



- Excavators are suitable for the soil extraction and move to a very short distance (relocation).
- Continuous excavators (multibucket trencher)
- Intermittent excavators-Slewing excavators



Cable-operated excavators



Front shovel



- 1. bogie undercarriage
- 2. slewing upper machinery (drive,
- operator's canopy, counter-weight)
- 3. turn mechanism
- 4. boom
- 5. arm
- 6. bucket
- 7. cable-lines

Features:

- · complicated driving system
- many moving elements \rightarrow manifold potential failures
- low working performance
- extensive maintenance requirements

Cable-operated excavators



- Intermittent (cyclic) operation
- Attachments: showel, hook, dragline, clamshell, boring equipment





Backacter, wheel-mounted



Front shovel, track-mounted

Hydraulic excavators (slewing excavators)

- 1. frame (carriage)
- 2. slewing upper machinery (engine, operator's canopy, counter-weight)
- 3. hoe (showel or bucket)
- 4. arm
- 5. boom (monoblock or articulated)
- 6. hoe rods
- 7. boom lifting cylinder
- 8. arm moving cylinder
- 9. hoe moving cylinder
- 10. outrigger (strut, jack)
- 11. auxiliary attachment (blade)



Excavator (in action)



Wheel-mounted backacter slewing excavator

Hydraulic excavators (slewing excavators)

- wheel-bogie
 turn mechanism
 slewing upper machinery
 boom
 arm
- 6. backacter
- 6. Dackacler
- 7. boom cylinders
- 8. arm cylinder
- 9. bucket cylinder
- 10. bucket moving rods
- 11. auxiliary attachment
- 12. outrigger





10. Bucket moving rods



Track-mounted front shovel slewing excavator





Clamshell bucket (for granular material)



Screening adapter (for recycled material)



Breakers, Jaws (for concrete, reinforced concrete and steel)

Others: loader bucket; drill; trunk-grip; cutter; trencher; fingered grips (for fibers or bars); crusher; vibro-plate; etc.



Sheet-wall piling equipment



Fingered grip



Boring (auger) equipment



Crusher adapter

Hydraulic excavator attachments

Backacter bucket



Auger

Ripper

Others: loading attachment; surface vibrator; roller compactor; bucket-lined or rotary terncher; profile buckets; sheet-wall driver; etc.



Clamshell

Earthwork attachments

Hydraulic excavator attachments Earthwork attachmenst a) e) g) hl i) Special bucket-typed attachments

a. drainer; b. ripper; c. canal maintainer; d. ripper-cleaner; e. profile bucket; f. extended cutter; g. ripper-profiler; h. ejector; i. tamper



a. clamshell; b. boring; c. fingered; d. bale grip; e. barrel/pipe grip; f. logger

Backhoe excavators



- 1. wheel tractor 2. backacter
- 3. arm
- 4. slewing boom
- 5. boom cylinder
- 6. arm cylinder
- 7. bucket cylinder
- 8. slewing mechanism
- 9. suspension (base) plate
- 10. outrigger
- 11. front attachment (loader)




Excavators



Backacter's working range (trajectory)

Loading machines



- Wheel-mounted
- Caterpillar
- With telescopic beam











Compaction by static weight*

- Roller wheel
- Steel runner
- Rubber wheel
- Cammed wheels

Compaction by vibration*

- Vibro-plates
- Tampers
- Type of use:
- Self-propelled
- Towed





Towed rollers

Basic types:



a. rubber-wheel roller



b. barefaced steel-drum



c. tamping (spiked/cammed) roller (for clay and adherent soil)

Features:

- Main application is soil compaction
- Towed individually or in groups
- Static load transferred to the soil can be controlled by weights mounted



Towed group of static rollers

Self-propelled rollers



Vibratory compaction

Principle of vibratory compaction:

Grains of soil are effected by periodically alternating inertial forces. These forces make grain particles 'floating', so ordering is progressed without friction.

At vibratory compaction low amplitude high frequency excitation is used for loose soil or for deep layers. High amplitude low frequency excitation is used for cohesive soils in thin layers. Frequency of excitation should be close to characteristic frequency of the soil.

Ways of excitation:

- circular excitation: simple construction, single exciter unit, eccentric should always rotate in direction of advancing
- directed excitation: double exciter unit, generates both compressing and sharing forces in the soil simultaneously
- oscillation: the two exciter masses generate moment at the surface of the drum creating compressing and sharing forces in the soil, so grains are ordered horizontally. Vertical force is provided by the weight of the drum







Double engine drive (both roller wheels are driven)

Vibratory roller remote control

- 1. vibro roller
- 2. exciter unit
- 3. controlling unit
- 4. monitor
- 5. acceleration sensor
- radio receiver-transmitter (database + controllingmonitoring system)
- 7. satellite
- 8. adjusting direction angle

Controlling parameters:

dynamic elastic modulus of material to be compacted (via measuring acceleration)

Controlled parameters:

vertical excitation force (F_{ve}) frequency of vibration working direction of the unit











Tampers can be used for to compact nearly all types of soil. Thickness (depth) of layer can be compacted effectively is about 40 cm. Compaction frequency is between 2 and 15 Hz.



Cammed wheels*



- Static and vibration
- On a wet surface (clay with stones)
- To dry the terrain!
- We can change the weight of the drums with sand and water filling.
- With steel and rubber wheel



