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ClearAll[A1, A2, x1, x2]
GT = {{-Cos[α], -Sin[α]}, {-1, 0}}
{{-Cos[α], -Sin[α]}, {-1, 0}}
G = Transpose[GT]
{{-Cos[α], -1}, {-Sin[α], 0}}
q = {0, P}
{0, P}
s = -Inverse[G].q
{P Csc[α], -P Cot[α]}
L2 = L
L
L1 = L / Cos[α]
L Sec[α]
F = {{L1 / Ym / A1, 0}, {0, L2 / Ym / A2}}
{L Sec[α] / A1 Ym, 0}, {0, L / A2 Ym}}
V = -Inverse[GT].F.s
{-L P Cot[α] / A2 Ym, L P Cot[α]^2 / A2 Ym + L P Csc[α]^2 Sec[α] / A1 Ym}

Feladat Átrendezője:
A2 = P / x1 / σH
A1 = P / x2 / σH

$$\frac{P}{x_1 \sigma H}$$


$$\frac{P}{x_2 \sigma H}$$

cf = A1 / Cos[α] + A2

$$\frac{P}{x_1 \sigma H} + \frac{P \operatorname{Sec}[α]}{x_2 \sigma H}$$

V[[1]] Ym / L / σH
V[[2]] Ym / L / σH // Simplify

$$-x_1 \operatorname{Cot}[\alpha] + x_2 \operatorname{Csc}[\alpha]^2 \operatorname{Sec}[\alpha]$$


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